Dr. Abhinav Malviya

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Research Area- Robotics, Crowd Simulation, Autonomous Vehicle Navigation, Artificial Intelligence **Education**:

• Dual Degree M.Tech. and Ph.D. in Information Technology Indian Institute of Information Technology (IIIT) Allahabad

Year of Completion: 2025

B.Tech. in Computer Science & Engineering
United College of Engineering & Research (UCER), Allahabad

Year of Completion: 2014

Publication:

International Journals – SCI/SCIE

- **1.** Malviya, A., & Kala, R. (2021). Social robot motion planning using contextual distances observe from 3D human motion tracking. *Expert Systems with Applications*, 184, 115515.(Impact factor 8.5)
- **2.** Malviya, A., & Kala, R. (2021). Learning-based simulation and modeling of unorganized chaining behavior using data generated from 3D human motion tracking. *Robotica*, 40(3), 544-569.

Conferences

- **1.** Malviya, A., & Kala, R. (2022, October). Risk Modeling of the Overtaking Behavior in the Indian Traffic. In *2022 IEEE 25th International Conference on Intelligent Transportation Systems* (*ITSC*) (pp. 2882-2887). IEEE.(Top conference in transportation)
- **2.** Malviya, A., Tripathi, D. V., Malviya, V., Kala, R.,(2025). Behaviour Conditioned Interactive Synthetic Dataset for Indoor Scenarios. In Advances in Robotics (AIR) (Accepted)

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